

Performance and Bottleneck Analysis

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Part 1

Methodology

Part 2

Measurements



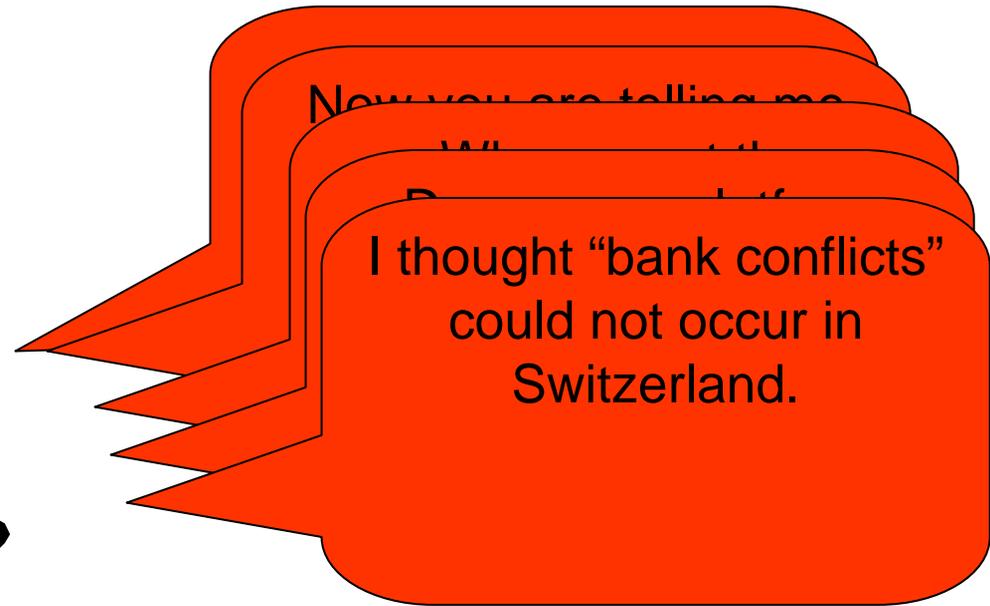
- How come we (too) often end up in the following situation?



Why the heck
doesn't it
perform as it
should!!!



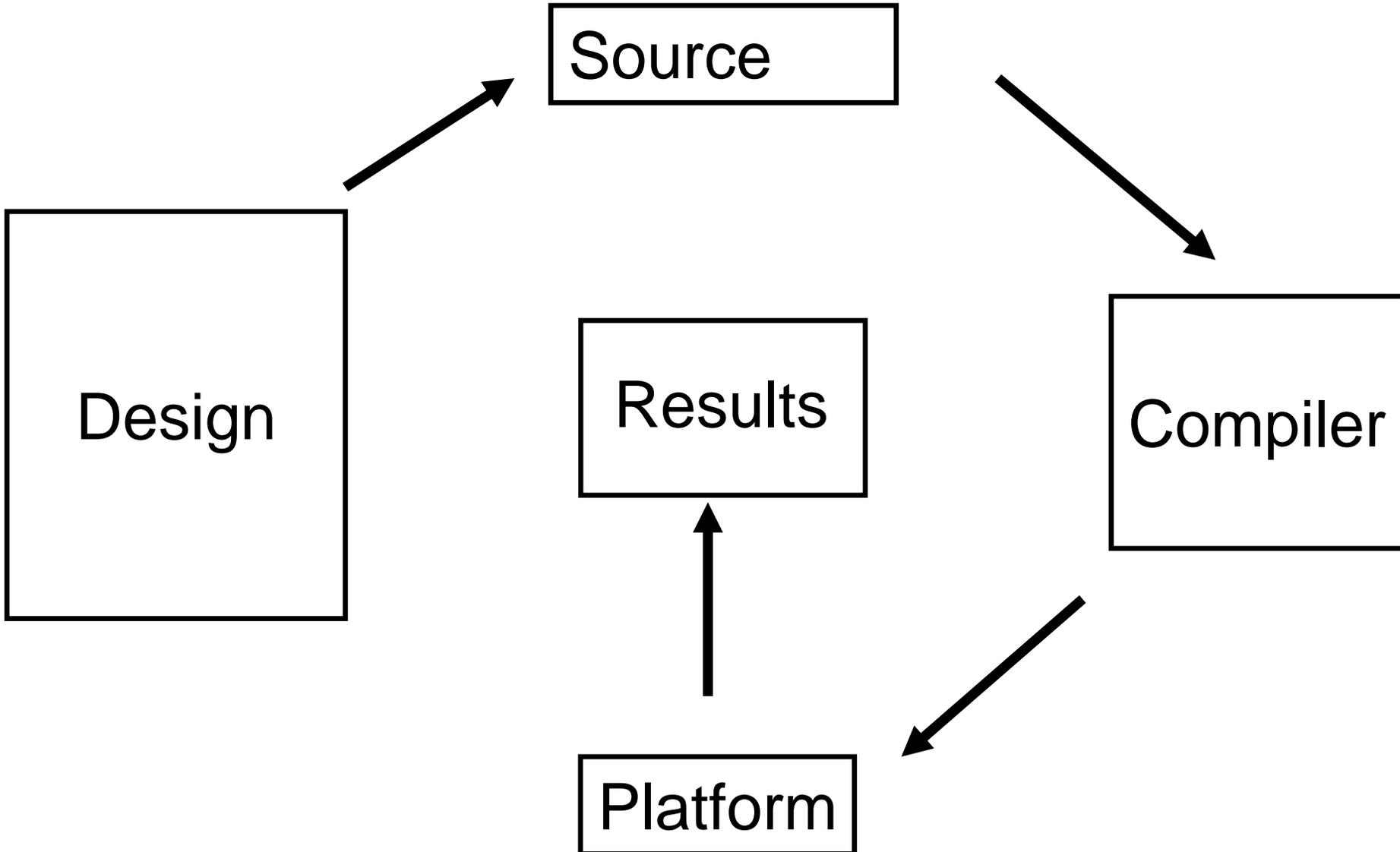
- In my opinion, there are many (complicated) details to worry about!





- **This is an effort to pass in review a somewhat “systematic approach” to tuning and bottleneck analysis**
 - Main focus is on understanding the “platform”
- **The introduction of the elements is done “top-down”**
- **But, it is important to understand that in real-life, however, the approach is likely to be “middle-out”**
 - And often “reduced” middle-out

The Planned Path





- **Choice of:**
 - Producer
 - Version
 - Flags
- **As well as:**
 - Build procedure
 - Library layout
 - Run-time environment
- **And (to a large extent):**
 - Machine code is then chosen for you.
- **For example:**
 - GNU, Intel, Pathscale, Microsoft,
 - gcc 3 or gcc 4 ?
 - How to choose from hundreds?
 - Compiling one class at a time?
 - Archive or shared?
 - Monolithic executable or dynamic loading?
 - Could influence via `-march=xxx`

By the way, who knows: `-xK/W/N/P/B` ?

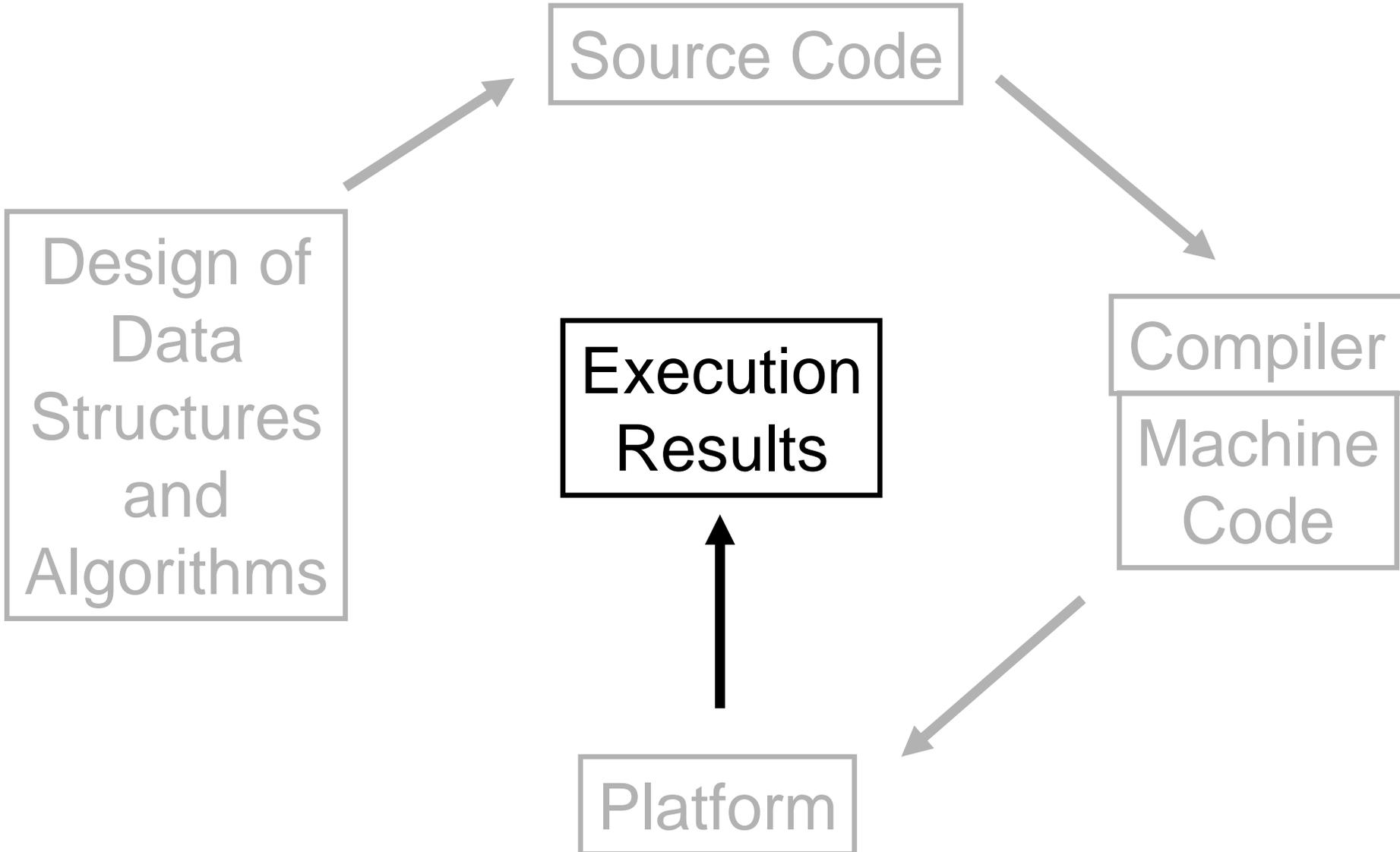


- **Choice of:**

- Manufacturer
- ISA
- Processor characteristics
 - Addressing
 - Frequency
 - Core layout
 - Micro-architecture
 - Cache organization
- Further configuration characteristics

- **Multiple options:**

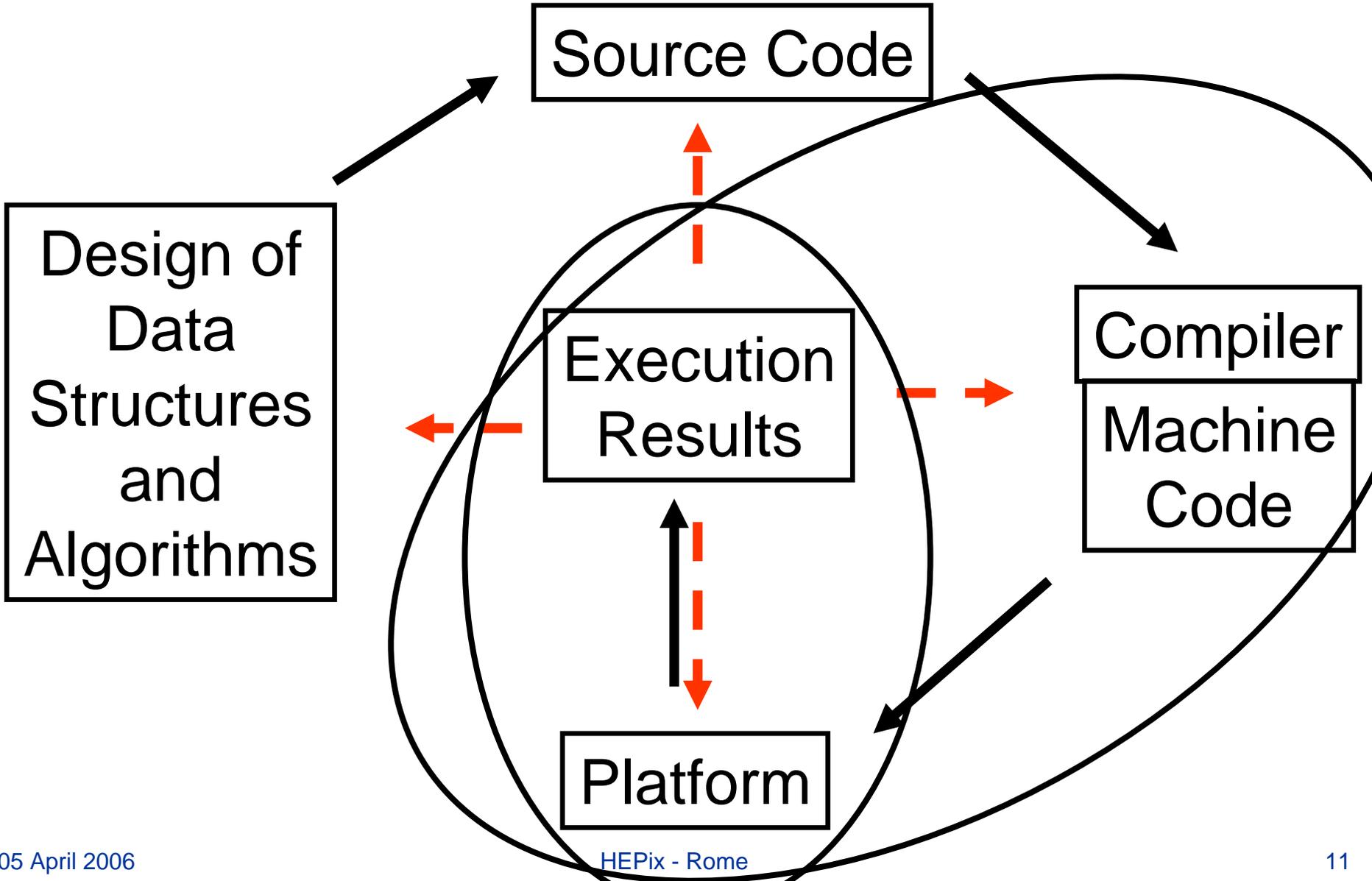
- AMD, Intel, Via, IBM, SUN, ..
- IA32, AMD64/EM64T, IA64, Power, Cell, SPARC, ..
- Could be:
 - 32- or 64-bit
 - 3.8 GHz Netburst or 2 GHz “Core” ?
 - Single, dual, quad core, ..
 - Pentium 4, Pentium M, AMD K7, ..
 - Different sizes, two/three levels, ..
- Bus bandwidth, Type/size of memory,





- **First of all, we must guarantee correctness**
- **If we are unhappy with the performance**
 - ... and by the way, how do we know when to be happy?
- **We need to look around**
 - Since the culprit can be anywhere

Where to look ?



Need a good tool set



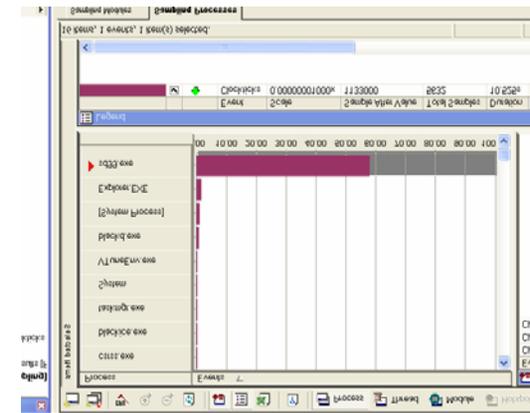
• My recommendation

– Integrated Development Environment (IDE) w/ integrated Performance Analyzer

- Visual Studio + VTUNE (Windows)
- Eclipse + VTUNE (Linux)
- XCODE + Shark (MacOS)
-

• Also, other packages

- Valgrind (Linux x86, x86-64)
- Qtools (IPF)
- Pfmmon, perfsuite, caliper, oprofile, TAU

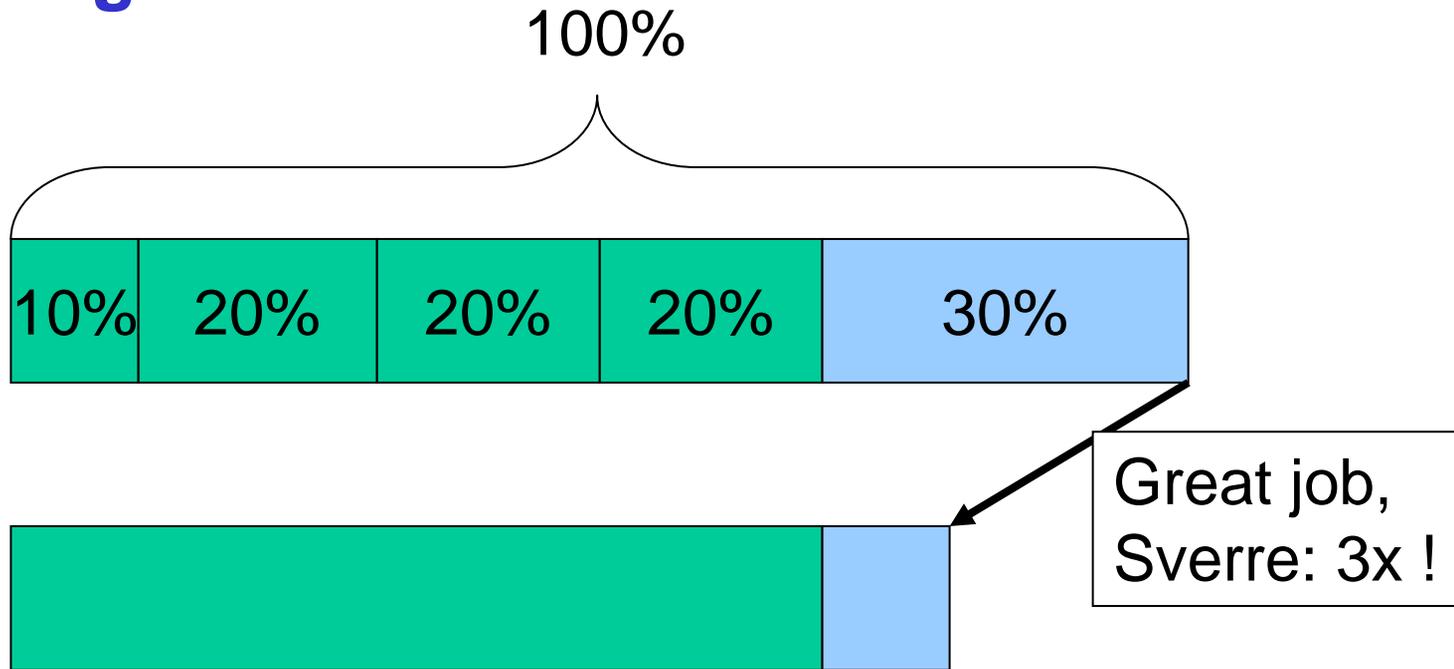




- In my opinion, High Energy Physics codes present (at least) two obstacles
 - Somewhat linked
- **One:** Cycles are spread across many routines
- **Two:** Often hard to determine when algorithms are optimal
 - In general
 - On a given h/w platform



- The incompressible part ends up dominating:



Total speedup is “only”: $(100/80): 1.25$

Typical profile

Stop press: G4ATLAS



Samples	Self %	Total %	Module
11767458	36.64%	36.64%	libG4geometry.so
5489494	17.09%	53.73%	libG4processes.so
2283674	7.11%	60.85%	libG4tracking.so
2146178	6.68%	67.53%	libm-2.3.2.so
2057144	6.41%	73.93%	libstdc++.so.5.0.3
1683623	5.24%	79.18%	libc-2.3.2.so
933872	2.91%	82.08%	libCLHEP-GenericFunctions-1.9.2.1.so
685894	2.14%	84.22%	libG4track.so
655282	2.04%	86.26%	libCLHEP-Random-1.9.2.1.so
524236	1.63%	87.89%	libpthread-0.60.so
283521	0.88%	88.78%	libCLHEP-Vector-1.9.2.1.so
265656	0.83%	89.60%	libG4materials.so
205836	0.64%	90.24%	libG4Svc.so
197690	0.62%	90.86%	libG4particles.so
190272	0.59%	91.45%	ld-2.3.2.so
150757	0.47%	91.92%	libCore.so (ROOT)
149525	0.47%	92.39%	libFadsActions.so
126111	0.39%	92.78%	libG4event.so
123206	0.38%	93.16%	libGaudiSvc.so



```
Double_t TRandom3::Rndm(Int_t){
  UInt_t y;
  const Int_t kM = 397; const Int_t kN = 624; const UInt_t kTemperingMaskB = 0x9
  const UInt_t kTemperingMaskC = 0xefc60000; const UInt_t kUpperMask = 0x800
  const UInt_t kLowerMask = 0x7fffffff; const UInt_t kMatrixA = 0x990

  if (fCount624 >= kN) {
    register Int_t i;
    for (i=0; i < kN-kM; i++) { /* THE LOOPS */
      y = (fMt[i] & kUpperMask) | (fMt[i+1] & kLowerMask);
      fMt[i] = fMt[i+kM] ^ (y >> 1) ^ ((y & 0x1) ? kMatrixA : 0x0);
    }
    for ( ; i < kN-1 ; i++) {
      y = (fMt[i] & kUpperMask) | (fMt[i+1] & kLowerMask);
      fMt[i] = fMt[i+kM-kN] ^ (y >> 1) ^ ((y & 0x1) ? kMatrixA : 0x0);
    }
    y = (fMt[kN-1] & kUpperMask) | (fMt[0] & kLowerMask);
    fMt[kN-1] = fMt[kM-1] ^ (y >> 1) ^ ((y & 0x1) ? kMatrixA : 0x0);
    fCount624 = 0;
  }
  y = fMt[fCount624++]; /*THE STRAIGHT-LINE PART*/
  y ^= (y >> 11); y ^= ((y << 7) & kTemperingMaskB);
  y ^= ((y << 15) & kTemperingMaskC); y ^= (y >> 18);
  if (y) return (Double_t) y * 2.3283064365386963e-10; // * Power(2,-32)
  return Rndm();
}
```



- **Highly optimized**

- Here depicted in 3 Itanium cycles

- But similarly dense on other platforms

0	Load	Test Bit	XOR	Load	Add	No-op
1	AND	AND	Shift	Add	Load	Move
2	Store	OR	XOR	Add	Add	Branch

The sequential part is not!



0	Add	Mov long	No-op	No-op	No-op	No-op
1	Load	Mov long	Mov long	No-op	No-op	No-op
2	Shift,11	Set float	No-op	No-op	No-op	No-op
3	XOR	Move	No-op	No-op	No-op	No-op
4	Shift,7	No-op	No-op	No-op	No-op	No-op
5	AND	No-op	No-op	No-op	No-op	No-op
6	XOR	No-op	No-op	No-op	No-op	No-op
7	SHL,15	No-op	No-op	No-op	No-op	No-op
8	AND	No-op	No-op	No-op	No-op	No-op
9	XOR	No-op	No-op	No-op	No-op	No-op
10	SHL,18	No-op	No-op	No-op	No-op	No-op
11	XOR	No-op	No-op	No-op	No-op	No-op
12	Set float	Compare	Branch	No-op	No-op	No-op
13	Bubble (no work dispatched)	<pre> y = fmt[fCount624++]; /*THE STRAIGHT-LINE PART*/ y ^= (y >> 11); y ^= ((y << 7) & kTemperingMaskB); y ^= ((y << 15) & kTemperingMaskC); y ^= (y >> 18); if (y) return ((Double_t) y * 2.3283064365386963e-10); </pre>				
14	Bubble (no work dispatched)					
15	Bubble (no work dispatched)					
16	Bubble (no work dispatched)					
17	Bubble (no work dispatched, because of FP latency)					
18	Mult FP	No-op	No-op	No-op	No-op	No-op
19	Bubble (no work dispatched, because of FP latency)					
20	Bubble (no work dispatched, because of FP latency)					
21	Bubble (no work dispatched, because of FP latency)					
22	Mult FP	Branch	No-op	No-op	No-op	No-op

“Low- hanging fruit”



- Typically one starts with a given compiler, and moves to:

- **More aggressive compiler options**

- For instance:
- -O2 → -O3, -funroll-loops, -ffast-math (g++)
- -O2 → -O3, -ipo (icc)

Some options can compromise accuracy or correctness

- **More recent compiler versions**

- g++ version 3 → g++ version 4
- icc version 8 → icc version 9

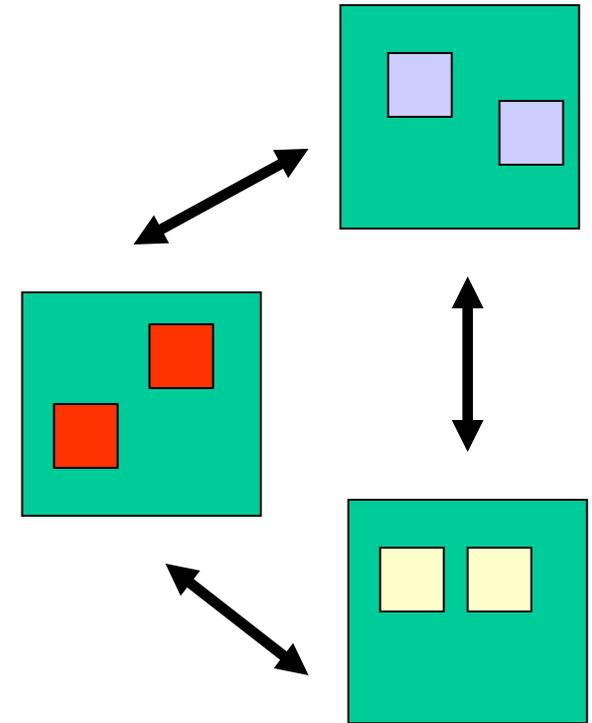
- **Different compilers**

- GNU → Intel or Pathscale
- Intel or Pathscale → GNU

May be a burden because of potential source code issues



- **Let the compiler worry about interprocedural relationship**
 - “icc -ipo”
- **Valid also when building libraries**
 - Archive
 - Shared
- **Cons:**
 - Can lead to code bloat
 - Longer compile times



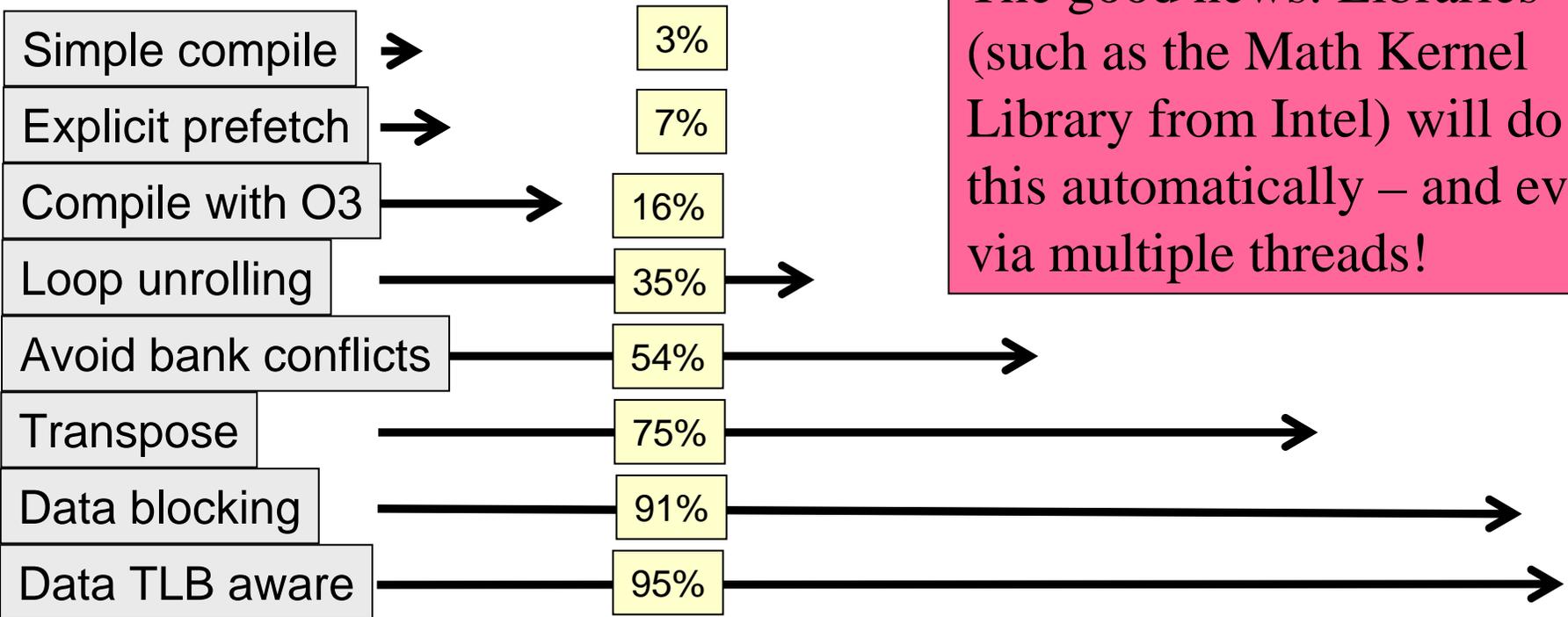
Probably most useful when combined with heavy optimization for “production” binaries or libraries!



- **Matrix multiply example (IPF)**

- From D.Levinthal/Intel (Optimization talk at IDF, spring 2003)

- Basic algorithm: $C_{ik} = \text{SUM} (A_{ij} * B_{jk})$



The good news: Libraries (such as the Math Kernel Library from Intel) will do this automatically – and even via multiple threads!



- Simplified:**

Decode:



Execute:



Retire:



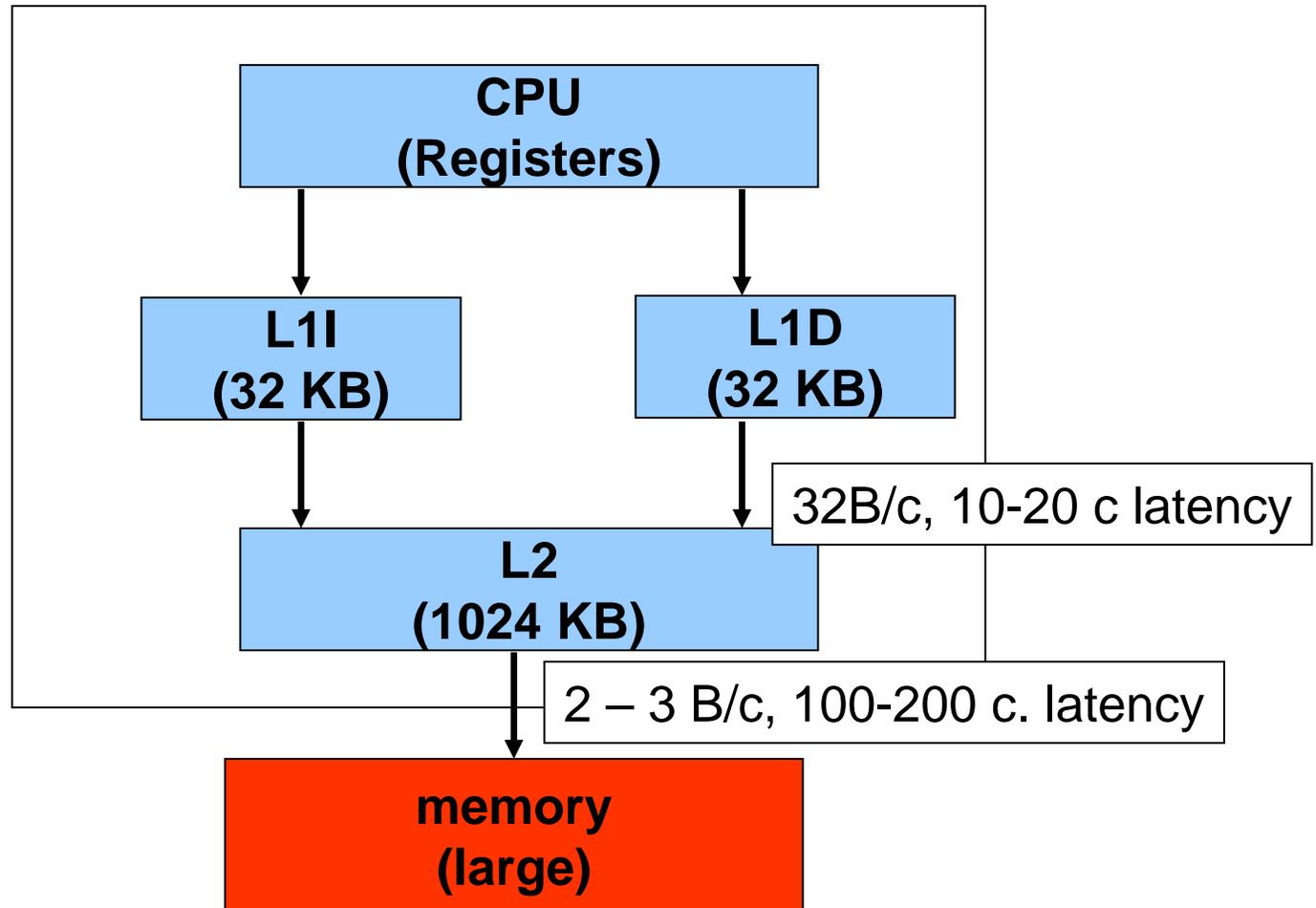
You also need to know how the execution units work: their latency and throughput.

Typical issue: Can this x86 processor issue a new SSE instruction every cycle or every other cycle?

Memory Hierarchy

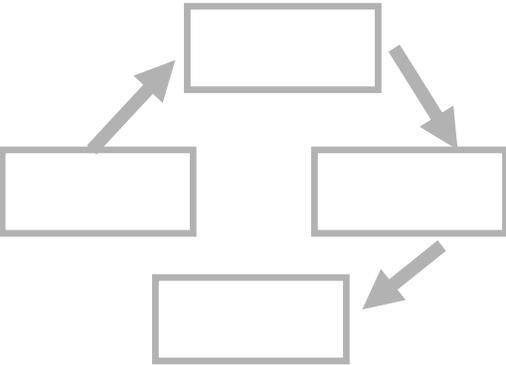


- From CPU to main memory



You should avoid direct dependency on memory (both latency and throughput)

Summing up



- **Understand which parts of the “circle” you control**
- **Equip yourself with good tools**
 - **Get access to hw performance counters**
 - Use IDE w/integrated performance tools
 - Threading analysis tools (?)
- **Check how key algorithms map on to the hardware platforms**
 - Are you at 5% or 95% efficiency?
 - Where do you want to be?
- **Cycle around the change loop frequently**
 - It is hard to get to “peak” performance!

Part 1
Methodology
Part 2
Measurements
(first results)



- **Special on-chip hardware of modern CPU**
 - Direct access to CPU counts of branch prediction, data and instruction caches, floating point instructions, memory operations
 - Event detectors, counters
 - Itanium2: 4 (12) counters, 100+ events to monitor
 - **Pentium 4, Xeon**: 44 event detectors, 18 counters
 - Linux interfaces and libraries:
 - Part of kernel in order to per-thread and per-system measurements
 - Perfmon2
 - uniform across all hardware platforms; event multiplexing
 - Full support mainly in the Itanium (integrated w/2.6 kernel)
 - **Perfctr**
 - per-thread and system-wide measurements
 - user and kernel domain; kernels 2.4 & 2.6; No multiplexing
 - Support for a lot of CPUs (P Pro/II/III/IV/Xeon), no support for Itanium
 - Almost no documentation apart from comments in source files
 - Require a deep understanding of performance monitoring features of every processors

Pentium 4 Performance Monitoring Features



- 44 event detectors, 9 pairs of counters
- 2 control registers (ESCR, CCCR)
- 2 classes of events:
 - **Non-retirement events** – those that occur any time during execution (1 counter)
 - **At-retirement events** – those that occurred on execution path and their results were committed in architectural state (1 or 2 counters)
- multiplexing

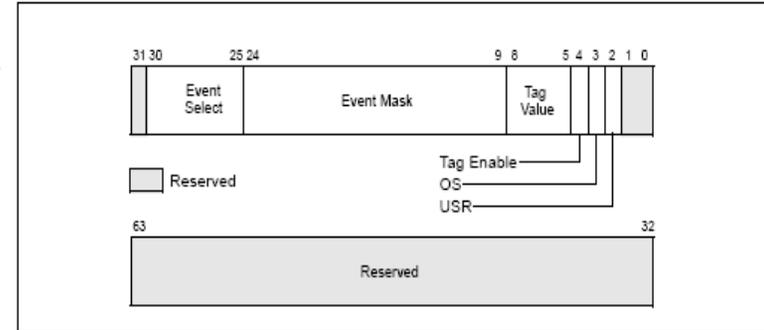


Figure 18-9. Event Selection Control Register (ESCR) for Pentium 4 and Intel Xeon Processors without HT Technology Support

from Intel documentation

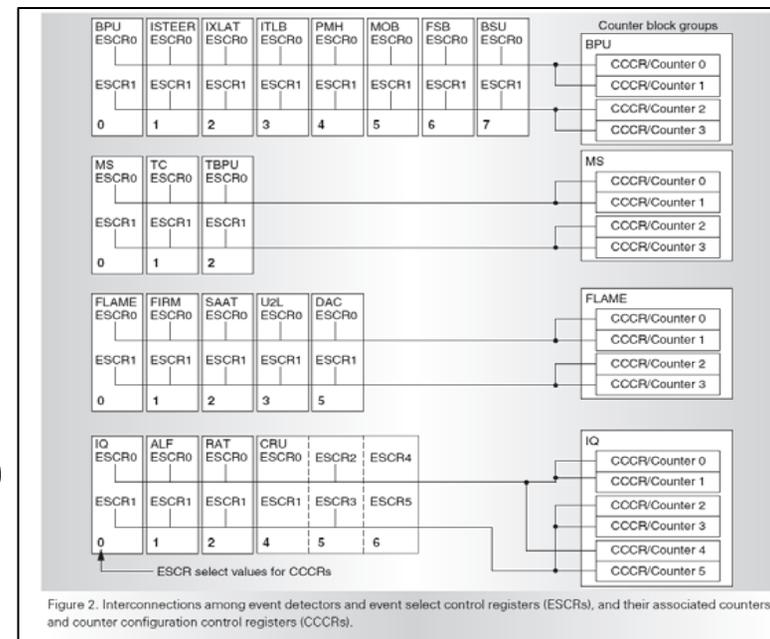


Figure 2. Interconnections among event detectors and event select control registers (ESCRs), and their associated counters and counter configuration control registers (CCCRs).

from B. Sprunt "Pentium 4 Performance-Monitoring Features"

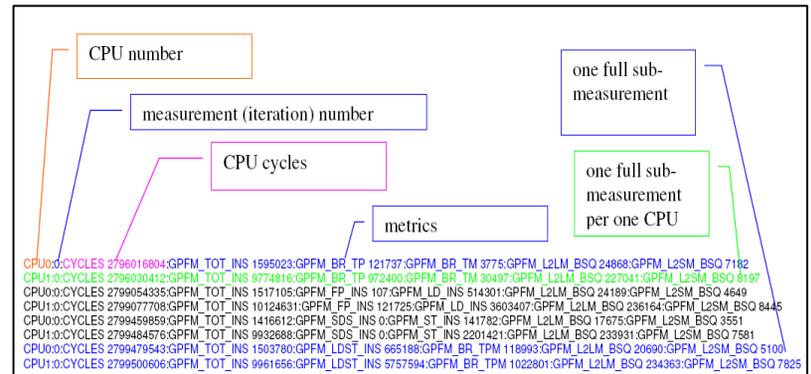
Monitoring tool - *gpfmon*



- uses **perfctr**
- enables **multiplexing**
- **user and kernel domain**
- **per single or total CPU**
- **events:**

CYC = CPU cycles
TOT = Instructions completed
BR_TP = Branch taken predicted
BR_TM = Branch taken mispredicted
L2LM = L2 load missed
L2SM = L2 store missed
FP = Floating point instructions
SDS = scalar instructions
LD = load instructions
ST = store instructions
BR = BR_TP+BR_TM
LDST = LD+ST

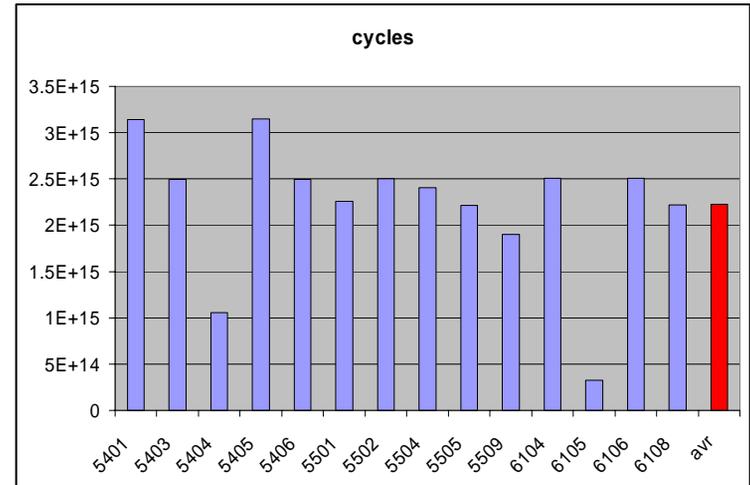
→	CYC	TOT	BR_TP	BR_TM	L2LM	L2SM
→	CYC	TOT	FP	LD	L2LM	L2SM
→	CYC	TOT	SDS	ST	L2LM	L2SM
→	CYC	TOT	LDST	BR	L2LM	L2SM



Ixbatch monitoring



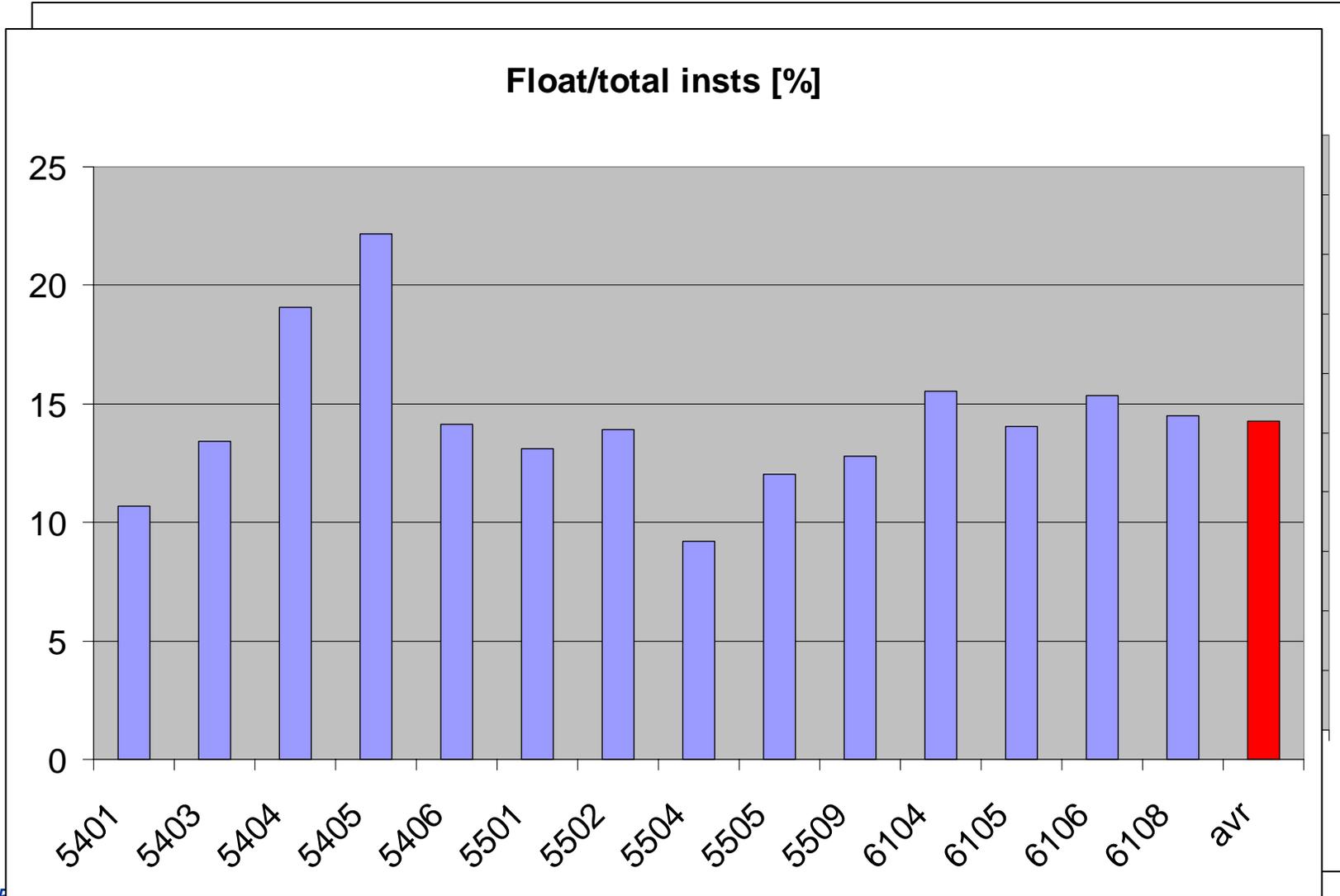
- 14 machines
- Running from 2 days to 2 weeks
- Nocona (10) – lxb5xxx
- Irwindale (4) – lxb6xxx
- 2.8 GHz
- Cache: 1 MB L2 (10) 2 MB L2 (4)
- SL3 (kernel 2.4)



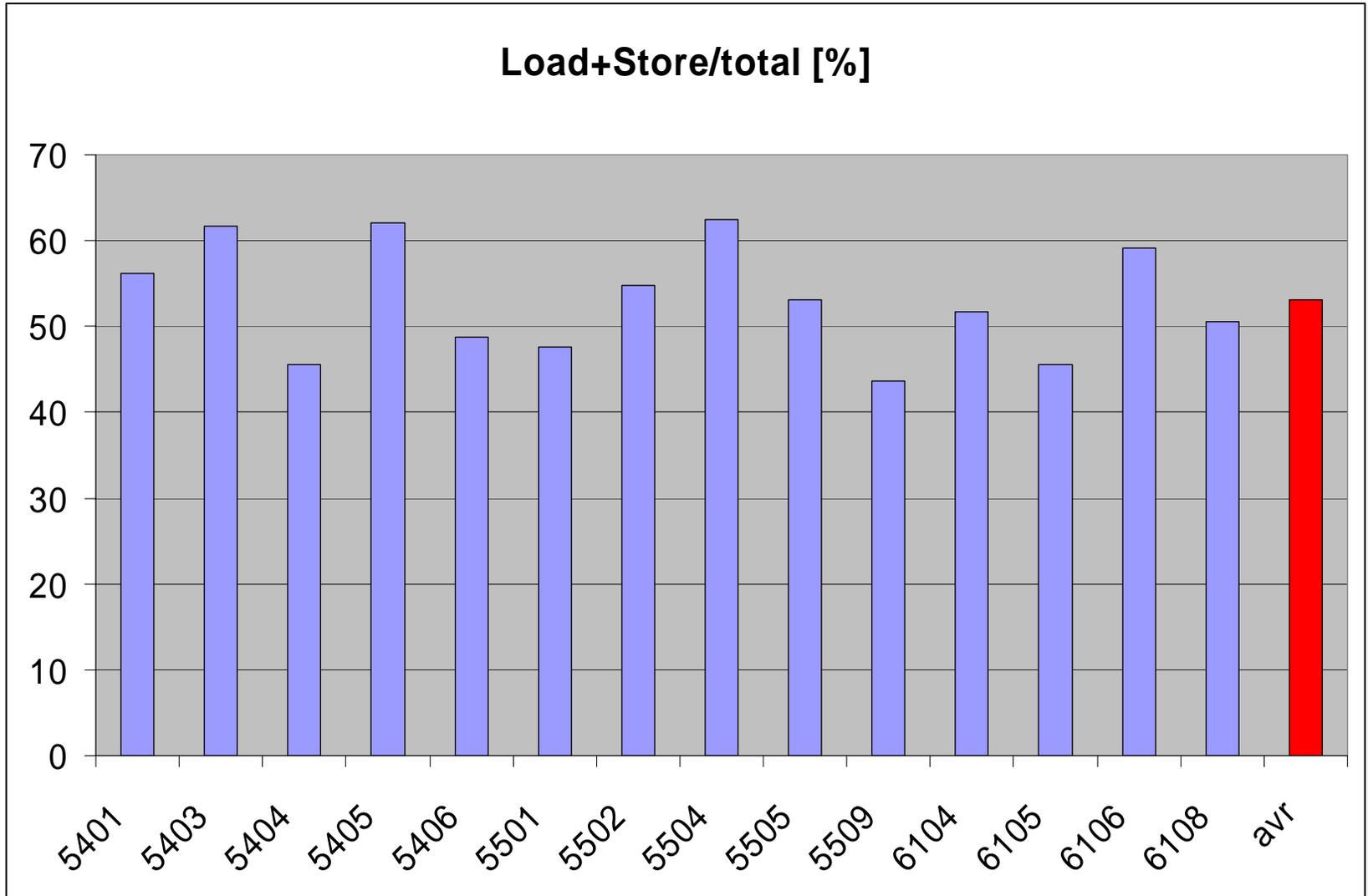
Ixbatch monitoring



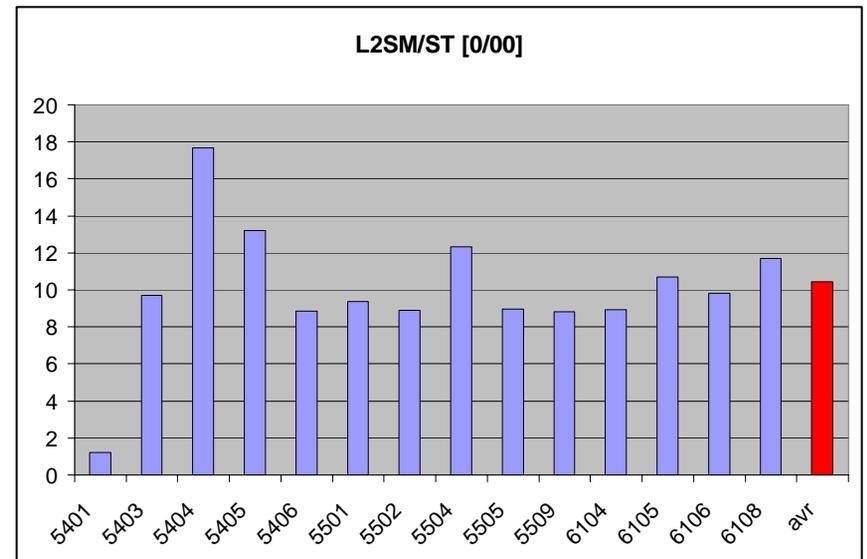
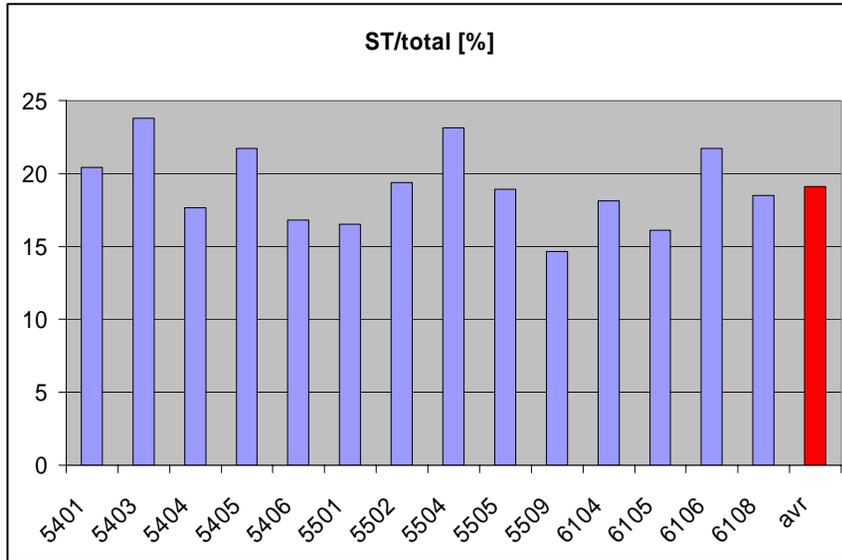
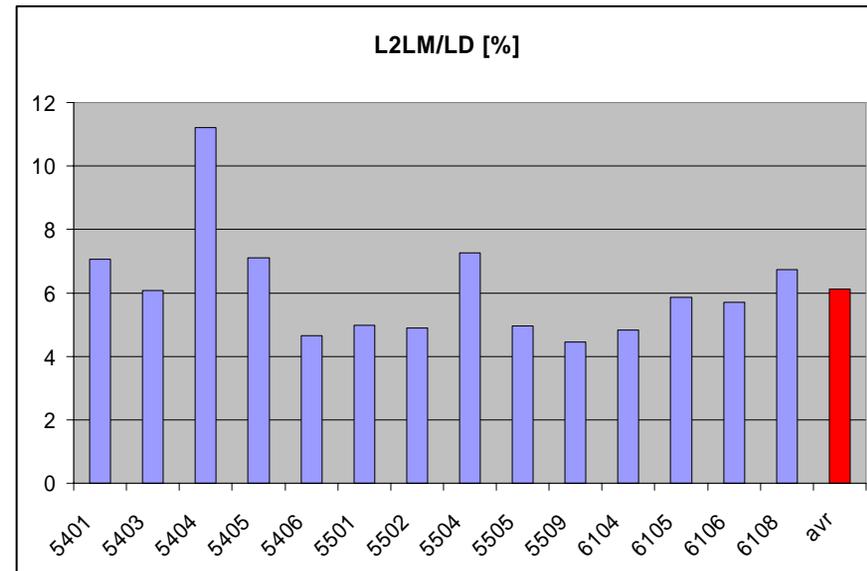
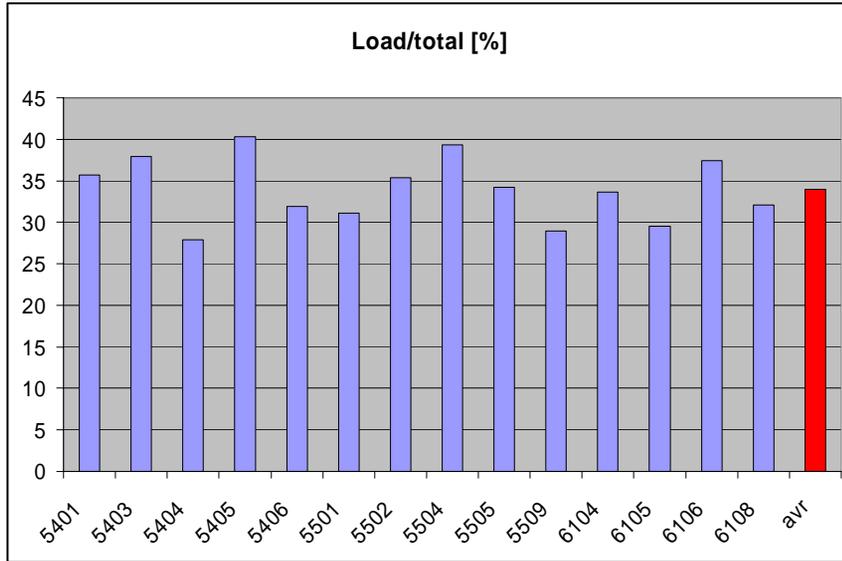
- Monitors everything: Kernel, User, both CPUs



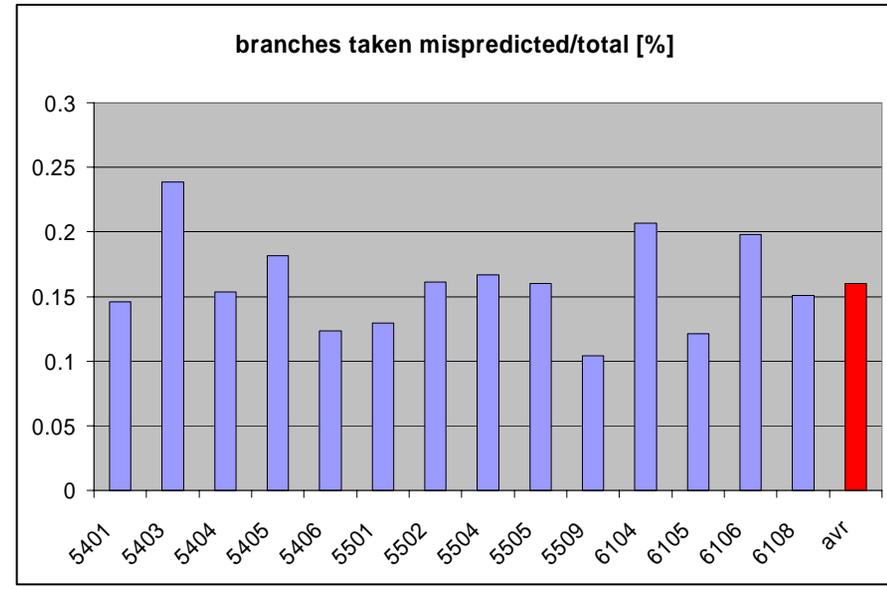
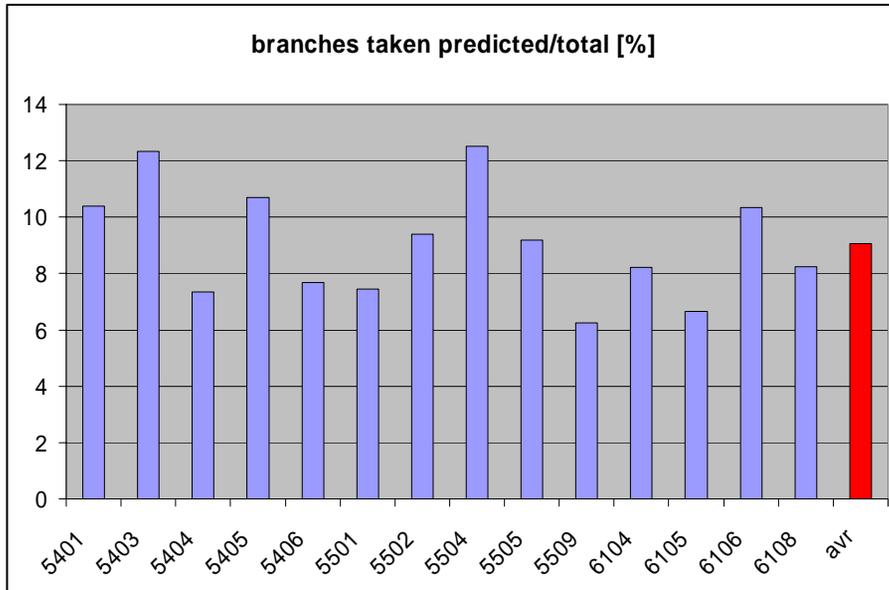
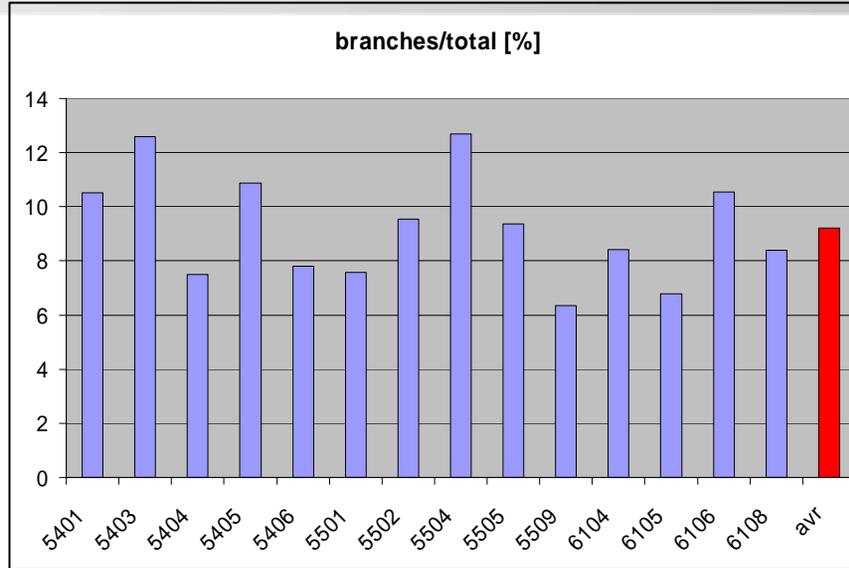
Ixbatch memory operations



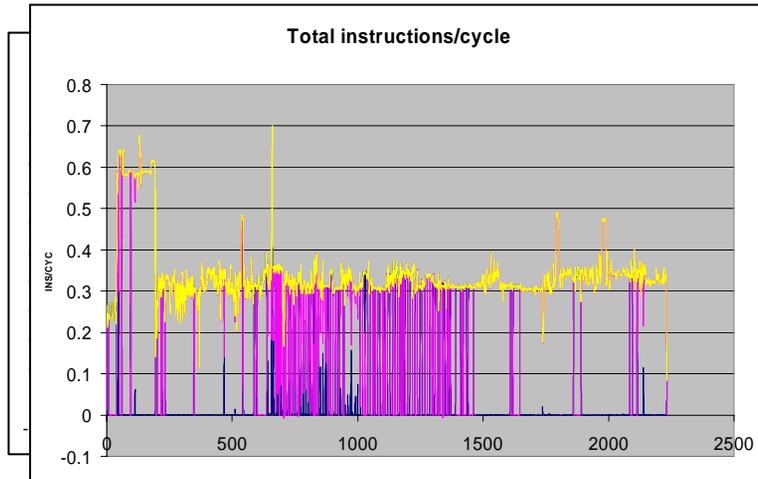
Ixbatch memory operations



Ixbatch - branches



G4Atlas simulation (3 events)

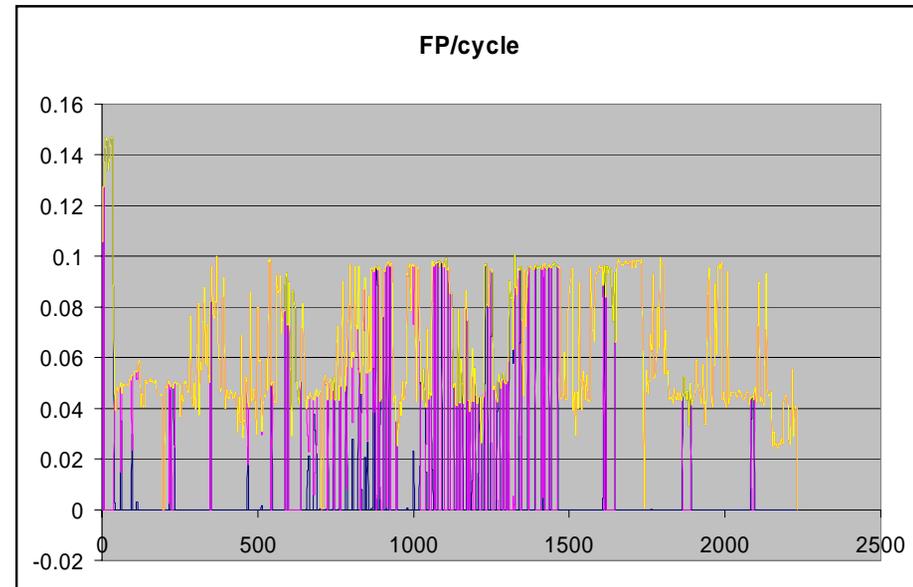


Total instructions

Cycles	6252 * 10⁹
Total inst	2136 * 10⁹
TOT INS/CYC	0.342

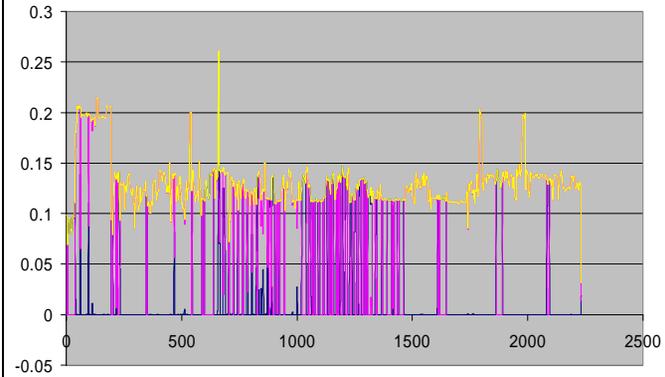
Floating-point instructions

FP	397 * 10⁹
FP/TOT	0.186





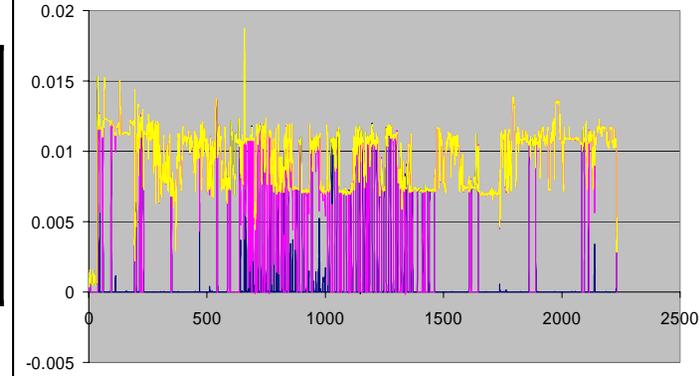
LD/cycle



Loads 38%

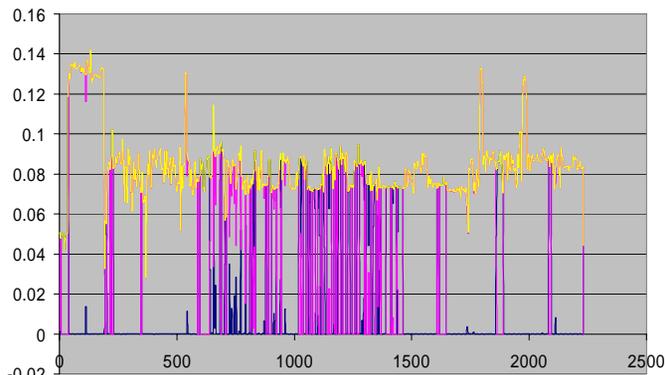
LD	$814 * 10^9$
LD/TOT	0.38
L2LM	$60 * 10^9$
L2LM/LD	0.074

L2LM/cycle



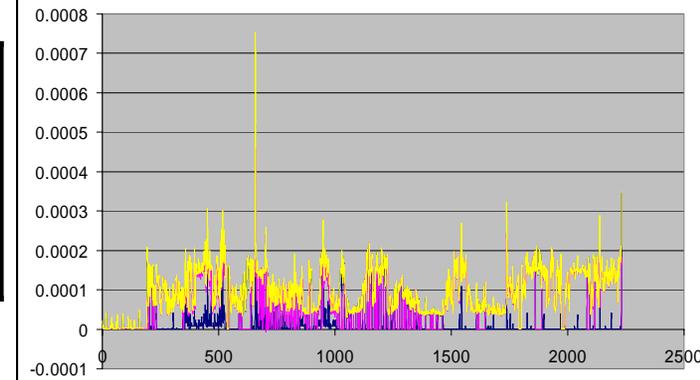
Stores 25%

ST/cycle

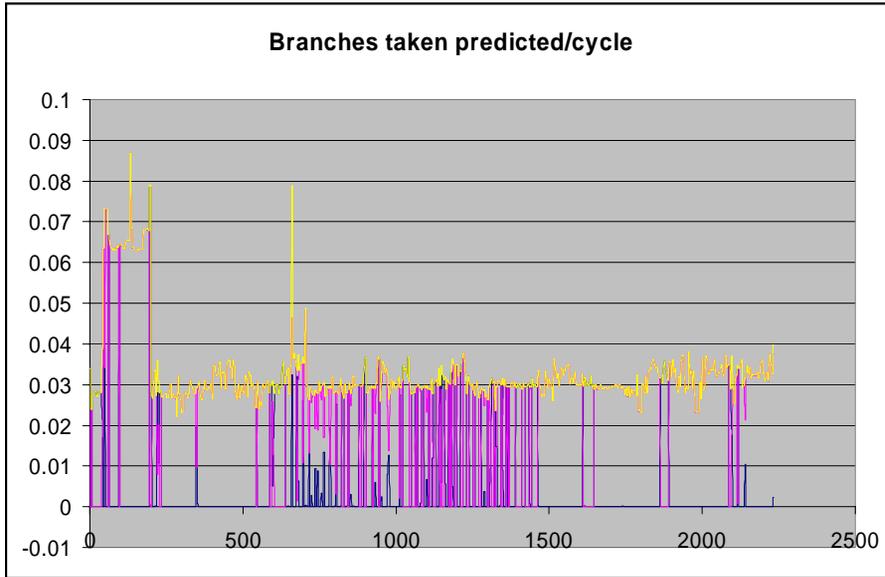


ST	$528 * 10^9$
ST/TOT	0.247
L2SM	$0.60 * 10^9$
L2SM/ST	0.00113

L2SM/cycle

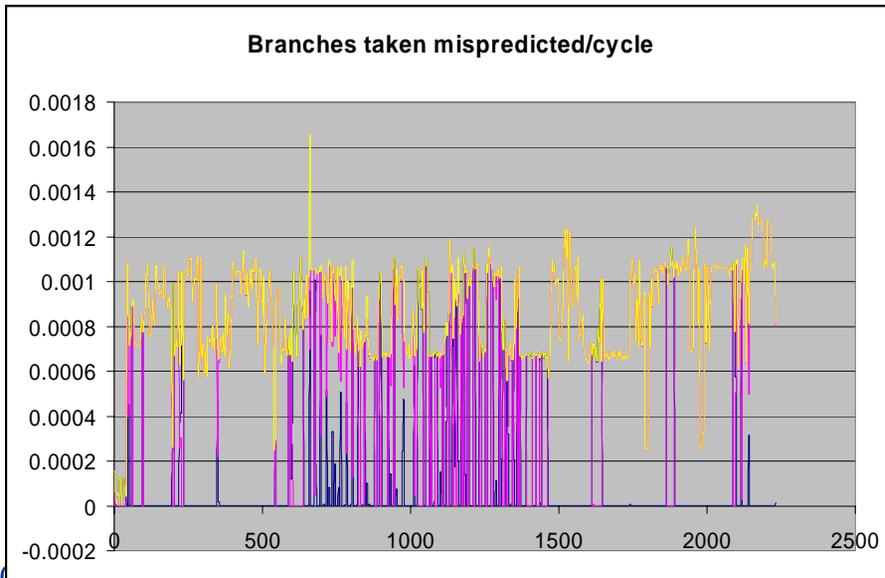


G4Atlas simulation



Branches 10%

BR_TP	218 * 10 ⁹
BR_TM	5.4 * 10 ⁹
BR_TP/TOT	0.097
BR_TM/TOT	0.00252





- **Counter by counter we see:**
 - Inst/Cycle:
 - Average 0.5 (from LXBATCH)
 - When G4ATLAS has received input file: 0.6 - 0.7
 - In any case, very far from 3 !!
 - Load + Store
 - 34 % + 18 % (38 % + 25 % for G4ATLAS)
 - Too many stores: Are jobs doing too much copying?
 - Total mix (lxbatch)
 - L + S: 52 %
 - FLP: 14 %
 - Branches taken: 9 %
 - Other: 25% → What are these?



- **Counter by counter we see:**
 - Branches Taken Predicted **incorrectly**
 - 2.7 % (of Branches Taken – G4ATLAS)
 - Probably OK, but need to check Branch-Not-Taken counts
 - L2 Store Misses:
 - 0.1% (of stores – G4ATLAS)
 - Very low, so OK
 - L2 Load Misses
 - 6 – 7 % (of loads)
 - Need to understand in more detail
 - Could be multiple hits for a single cache line
 - Cache size
 - 1 MB or 2 MB ?
 - Do not see fewer L2LD misses



QUESTIONS?



Backup



Design of
Data
Structures
and
Algorithms

- **Choice of algorithms for solving our problems:**
 - Accuracy, Robustness, Rapidity
- **Choice of data layout**
 - Structure
 - Types
 - Dimensions
- **Design of classes**
 - Interrelationship
 - Hierarchy



- **Choice of**

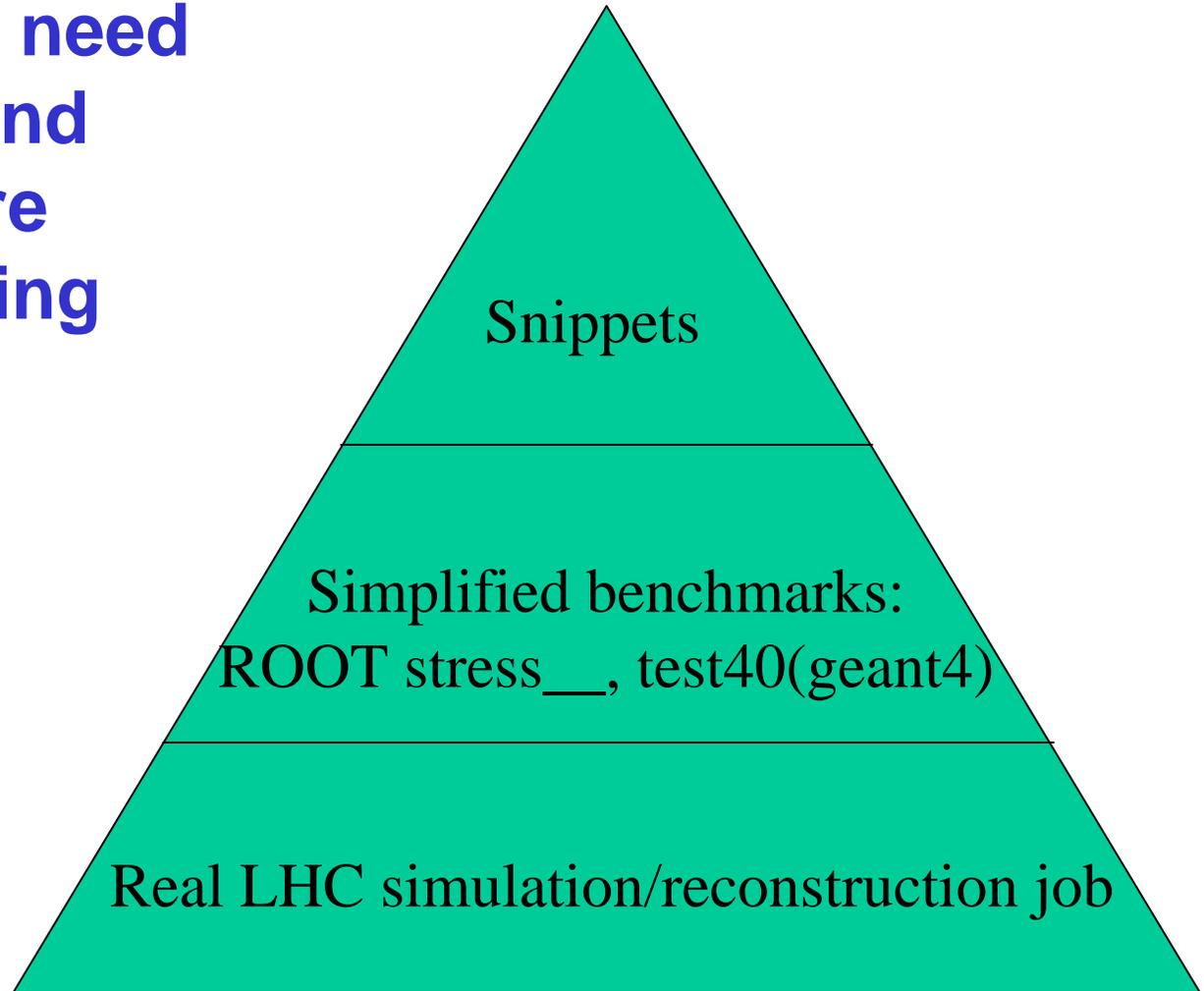
- Implementation language
- Language features &
- Style
- Precision (FLP)
- Source structure and organization
- Use of preprocessor
- External dependencies
- ...

- **For example**

- Fortran, C, C++, Java, ..
- In **C++**: Abstract classes, templates, etc.
- Single, double, double extended, ..
- Contents of .cpp and .h
- Aggregation or decomposition
- Platform dependencies (such as endianness)
- Smartheap, Math kernel libraries, ...



- You always need to understand what you are benchmarking





- It may be necessary to read the machine code

```

.LFB1840:
    movsd    16(%rsi), %xmm2
    movsd    .LC2(%rip), %xmm0
    xorl     %eax, %eax
    movsd    8(%rdi), %xmm4
    andnpd   %xmm2, %xmm0
    ucomisd  %xmm4, %xmm0
    ja       .L22
    movsd    (%rsi), %xmm5
    movsd    8(%rsi), %xmm0
    movapd   %xmm2, %xmm3
    movsd    32(%rdi), %xmm1
    addsd    %xmm4, %xmm3
    mulsd    %xmm0, %xmm0
    mulsd    %xmm5, %xmm5
    addsd    %xmm0, %xmm5
    movapd   %xmm4, %xmm0
    mulsd    %xmm3, %xmm1
    subsd    %xmm2, %xmm0
    mulsd    40(%rdi), %xmm3
    movapd   %xmm0, %xmm2
    movsd    16(%rdi), %xmm0
                                mulsd    %xmm2, %xmm0
                                mulsd    24(%rdi), %xmm2
                                addsd    %xmm0, %xmm1
                                movsd    .LC3(%rip), %xmm0
                                addsd    %xmm2, %xmm3
                                mulsd    %xmm0, %xmm1
                                mulsd    %xmm0, %xmm3
                                divsd    %xmm4, %xmm1
                                divsd    %xmm4, %xmm3
                                mulsd    %xmm1, %xmm1
                                ucomisd  %xmm5, %xmm1
                                ja       .L28
                                mulsd    %xmm3, %xmm3
                                movl     $1, %eax
                                ucomisd  %xmm3, %xmm5
                                jbe     .L22
.L28:
    xorl     %eax, %eax
.L22:
    ret

```



- **Many compilers allow further optimization through training runs**
 - Compile once (to instrument binary)
 - g++ -fprofile-generate
 - icc -prof_gen
 - Run one (or several test cases)
 - ./test40 < test40.in (will run slowly)
 - Recompile w/feedback
 - g++ -fprofile-use
 - icc -prof_use (best results when combined with -O3,-ipo)

With icc 9.0 we get ~20% on root stress tests on Itanium, but only ~5% on x86-64



- For instance: 4-way associativity

0	64B cache line	64B cache line	64B cache line	64B cache line
1	64B cache line	64B cache line	64B cache line	64B cache line
2	64B cache line	64B cache line	64B cache line	64B cache line
3	64B cache line	64B cache line	64B cache line	64B cache line

...

60	64B cache line	64B cache line	64B cache line	64B cache line
61	64B cache line	64B cache line	64B cache line	64B cache line
62	64B cache line	64B cache line	64B cache line	64B cache line
63	64B cache line	64B cache line	64B cache line	64B cache line